

(Trigonometry and Matrices)

Time Allowed : 3 Hrs.

Maximum Marks : 30

Note : (i) Attempt five questions in all, by selecting at least two questions from each Unit.

(ii) All questions carry equal marks.

UNIT-I

1. (a) Prove that four roots of the equation :

$$16z^4 - 20z^2 + 5 = 0 \text{ are } \pm \sin \frac{\pi}{5}, \pm \sin \frac{2\pi}{5}. \quad 3,3$$

(b) Define Primitive n^{th} root of unity and prove each Primitive 6th root of unity satisfies $x^2 - x + 1 = 0$. 3,3

2. (a) If $\tan(x + iy) = \sin(p + iq)$. Then prove :
 $\coth q \sinh 2y = \cot p \sin 2x$.

(b) If α, β are roots of $z^2 - 2z + 2 = 0$ then prove :

$$\frac{(x + \alpha)^n - (x + \beta)^n}{\alpha - \beta} = \frac{\sin n \phi}{\sin^n \phi}, x + 1 = \cot \phi. \quad 3,3$$

3. (a) If the principal values are considered, prove :

$$\frac{(1+i)^{1-i}}{(1-i)^{1+i}} = \sin(\log 2) + i \cos(\log 2).$$

(b) Prove $1 + \frac{1}{3} - \frac{1}{5} + \frac{1}{7} - \dots = \frac{\pi}{2\sqrt{3}}$. 3,3

4. (a) Sum the series to n terms.

$$\cot^{-1}(2 \cdot 1^2) + \cot^{-1}(2 \cdot 2^2) + \cot^{-1}(2 \cdot 3^2) + \dots$$

(b) Express $\cos^6 \theta \sin^4 \theta$ in terms of cosines of multiples of θ . 3,3

UNIT-II

5. (a) Show that every Hermitian matrix A can be uniquely expressed as $R + iS$, R, S are real symmetric and real skew-symmetric. Also show $A^{\theta} A$ is real iff $RS = -SR$.

(b) Under that condition on the scalar $\lambda \in \mathbb{R}$, are the vectors $(\lambda, 1, 0), (1, \lambda, 1)$ and $(0, 1, \lambda)$ linearly dependent? 3,3

6. (a) Let $A_{3 \times 3}$ matrix of rank 1 and B be 3×1 matrix. Show rank of $[A|B]$ is either 1 or 2.

(b) Do the following equations have a non-zero solution :
 $x - 2y - z = 0$, $2x + 5y + 2z = 0$, $x + 4y + 7z = 0$,
 $x + 3y + 3z = 0$.

3,3

7. (a) Reduce $A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 3 & 5 & 8 \\ 3 & 4 & 7 & 11 \end{bmatrix}$ to normal form.

(b) If λ is an eigen value of a non-singular matrix A, prove then $\frac{|A|}{\lambda}$ is an eigen-value of $\text{adj } A$.

3,3

8. (a) State Cayley-Hamilton Theorem. Hence, using it find inverse of

matrix $A = \begin{bmatrix} 2 & 6 & 1 \\ 0 & 1 & -6 \\ 3 & 4 & -2 \end{bmatrix}$.

(b) Define diagonalizable matrix. If $A = \begin{bmatrix} 3 & 2 & 0 \\ 2 & 0 & 0 \\ 1 & 0 & 2 \end{bmatrix}$ then diagonalize A.

3,3